

Algorithmic Threshold for Multi-Species Spin Glasses

Mark Sellke

University of Waterloo Statistics and Actuarial Science Seminar
Joint work with Brice Huang (MIT)



Motivating Example: Tensor PCA

Fix $p \geq 2$. Recover signal $\mathbf{x}_0 \in S_N = \sqrt{N}\mathbb{S}^{N-1}$ from noisy tensor observation

$$\mathbf{T} = \lambda \mathbf{x}_0^{\otimes p} + \mathbf{G}^{(p)}, \quad \mathbf{G}^{(p)} \in (\mathbb{R}^N)^{\otimes p} \text{ has i.i.d. } \mathcal{N}(0, 1) \text{ entries}$$

- E.g. $\mathbf{x}_0^{\otimes 2} \in \mathbb{R}^{N \times N}$ is a matrix with (i, j) entry $x_i x_j$.

Motivating Example: Tensor PCA

Fix $p \geq 2$. Recover signal $\mathbf{x}_0 \in S_N = \sqrt{N}\mathbb{S}^{N-1}$ from noisy tensor observation

$$\mathbf{T} = \lambda \mathbf{x}_0^{\otimes p} + \mathbf{G}^{(p)}, \quad \mathbf{G}^{(p)} \in (\mathbb{R}^N)^{\otimes p} \text{ has i.i.d. } \mathcal{N}(0, 1) \text{ entries}$$

- E.g. $\mathbf{x}_0^{\otimes 2} \in \mathbb{R}^{N \times N}$ is a matrix with (i, j) entry $x_i x_j$.
- Applications to topic modelling (Anandkumar-Ge-Hsu-Kakade-Telgarsky 12), collaborative filtering, hypergraph matching (Duchenne-Bach-Kwon-Ponce 09)

Motivating Example: Tensor PCA

Fix $p \geq 2$. Recover signal $\mathbf{x}_0 \in S_N = \sqrt{N}\mathbb{S}^{N-1}$ from noisy tensor observation

$$\mathbf{T} = \lambda \mathbf{x}_0^{\otimes p} + \mathbf{G}^{(p)}, \quad \mathbf{G}^{(p)} \in (\mathbb{R}^N)^{\otimes p} \text{ has i.i.d. } \mathcal{N}(0, 1) \text{ entries}$$

- E.g. $\mathbf{x}_0^{\otimes 2} \in \mathbb{R}^{N \times N}$ is a matrix with (i, j) entry $x_i x_j$.
- Applications to topic modelling (Anandkumar-Ge-Hsu-Kakade-Telgarsky 12), collaborative filtering, hypergraph matching (Duchenne-Bach-Kwon-Ponce 09)
- Max-likelihood estimator is **non-convex**, **random** optimization problem:

$$\mathbf{x}^{MLE} = \arg \max_{\mathbf{x} \in S_N} \langle \mathbf{T}, \mathbf{x}^{\otimes p} \rangle$$

Motivating Example: Tensor PCA

Fix $p \geq 2$. Recover signal $\mathbf{x}_0 \in S_N = \sqrt{N}\mathbb{S}^{N-1}$ from noisy tensor observation

$$\mathbf{T} = \lambda \mathbf{x}_0^{\otimes p} + \mathbf{G}^{(p)}, \quad \mathbf{G}^{(p)} \in (\mathbb{R}^N)^{\otimes p} \text{ has i.i.d. } \mathcal{N}(0, 1) \text{ entries}$$

- E.g. $\mathbf{x}_0^{\otimes 2} \in \mathbb{R}^{N \times N}$ is a matrix with (i, j) entry $x_i x_j$.
- Applications to topic modelling (Anandkumar-Ge-Hsu-Kakade-Telgarsky 12), collaborative filtering, hypergraph matching (Duchenne-Bach-Kwon-Ponce 09)
- Max-likelihood estimator is **non-convex**, **random** optimization problem:

$$\mathbf{x}^{MLE} = \arg \max_{\mathbf{x} \in S_N} \langle \mathbf{T}, \mathbf{x}^{\otimes p} \rangle$$

- \mathbf{x}^{MLE} **NP-hard** even to approximate in worst case (Hillar-Lim 13)

Motivating Example: Tensor PCA

Fix $p \geq 2$. Recover signal $\mathbf{x}_0 \in S_N = \sqrt{N}S^{N-1}$ from noisy tensor observation

$$\mathbf{T} = \lambda \mathbf{x}_0^{\otimes p} + \mathbf{G}^{(p)}, \quad \mathbf{G}^{(p)} \in (\mathbb{R}^N)^{\otimes p} \text{ has i.i.d. } \mathcal{N}(0, 1) \text{ entries}$$

- E.g. $\mathbf{x}_0^{\otimes 2} \in \mathbb{R}^{N \times N}$ is a matrix with (i, j) entry $x_i x_j$.
- Applications to topic modelling (Anandkumar-Ge-Hsu-Kakade-Telgarsky 12), collaborative filtering, hypergraph matching (Duchenne-Bach-Kwon-Ponce 09)
- Max-likelihood estimator is **non-convex**, **random** optimization problem:

$$\mathbf{x}^{MLE} = \arg \max_{\mathbf{x} \in S_N} \langle \mathbf{T}, \mathbf{x}^{\otimes p} \rangle$$

- \mathbf{x}^{MLE} **NP-hard** even to approximate in worst case (Hillar-Lim 13)
- Convex relaxations suboptimal by $N^{(p-2)/4}$ factor (Montanari-Richard 14, Hopkins-Shi-Steurer 15)

Motivating Example: Tensor PCA

Fix $p \geq 2$. Recover signal $\mathbf{x}_0 \in S_N = \sqrt{N}S^{N-1}$ from noisy tensor observation

$$\mathbf{T} = \lambda \mathbf{x}_0^{\otimes p} + \mathbf{G}^{(p)}, \quad \mathbf{G}^{(p)} \in (\mathbb{R}^N)^{\otimes p} \text{ has i.i.d. } \mathcal{N}(0, 1) \text{ entries}$$

- E.g. $\mathbf{x}_0^{\otimes 2} \in \mathbb{R}^{N \times N}$ is a matrix with (i, j) entry $x_i x_j$.
- Applications to topic modelling (Anandkumar-Ge-Hsu-Kakade-Telgarsky 12), collaborative filtering, hypergraph matching (Duchenne-Bach-Kwon-Ponce 09)
- Max-likelihood estimator is **non-convex**, **random** optimization problem:

$$\mathbf{x}^{MLE} = \arg \max_{\mathbf{x} \in S_N} \langle \mathbf{T}, \mathbf{x}^{\otimes p} \rangle$$

- \mathbf{x}^{MLE} **NP-hard** even to approximate in worst case (Hillar-Lim 13)
- Convex relaxations suboptimal by $N^{(p-2)/4}$ factor (Montanari-Richard 14, Hopkins-Shi-Steurer 15)
- **Existing frameworks leave incomplete understanding of computational limits.**

Motivating Example: Tensor PCA

Fix $p \geq 2$. Recover signal $\mathbf{x}_0 \in S_N = \sqrt{N}S^{N-1}$ from noisy tensor observation

$$\mathbf{T} = \lambda \mathbf{x}_0^{\otimes p} + \mathbf{G}^{(p)}, \quad \mathbf{G}^{(p)} \in (\mathbb{R}^N)^{\otimes p} \text{ has i.i.d. } \mathcal{N}(0, 1) \text{ entries}$$

- E.g. $\mathbf{x}_0^{\otimes 2} \in \mathbb{R}^{N \times N}$ is a matrix with (i, j) entry $x_i x_j$.
- Applications to topic modelling (Anandkumar-Ge-Hsu-Kakade-Telgarsky 12), collaborative filtering, hypergraph matching (Duchenne-Bach-Kwon-Ponce 09)
- Max-likelihood estimator is **non-convex**, **random** optimization problem:

$$\mathbf{x}^{MLE} = \arg \max_{\mathbf{x} \in S_N} \langle \mathbf{T}, \mathbf{x}^{\otimes p} \rangle$$

- \mathbf{x}^{MLE} **NP-hard** even to approximate in worst case (Hillar-Lim 13)
- Convex relaxations suboptimal by $N^{(p-2)/4}$ factor (Montanari-Richard 14, Hopkins-Shi-Steurer 15)
- Existing frameworks leave incomplete understanding of computational limits.

What are the basic computational limits of random optimization problems?

Motivating Example: Tensor PCA

Fix $p \geq 2$. Recover signal $\mathbf{x}_0 \in S_N = \sqrt{N}\mathbb{S}^{N-1}$ from noisy tensor observation

$$\mathbf{T} = \lambda \mathbf{x}_0^{\otimes p} + \mathbf{G}^{(p)}, \quad \mathbf{G}^{(p)} \in (\mathbb{R}^N)^{\otimes p} \text{ has i.i.d. } \mathcal{N}(0, 1) \text{ entries}$$

- E.g. $\mathbf{x}_0^{\otimes 2} \in \mathbb{R}^{N \times N}$ is a matrix with (i, j) entry $x_i x_j$.
- Applications to topic modelling (Anandkumar-Ge-Hsu-Kakade-Telgarsky 12), collaborative filtering, hypergraph matching (Duchenne-Bach-Kwon-Ponce 09)
- Max-likelihood estimator is **non-convex, random** optimization problem:

$$\mathbf{x}^{MLE} = \arg \max_{\mathbf{x} \in S_N} \langle \mathbf{T}, \mathbf{x}^{\otimes p} \rangle$$

- \mathbf{x}^{MLE} **NP-hard** even to approximate in worst case (Hillar-Lim 13)
- Convex relaxations suboptimal by $N^{(p-2)/4}$ factor (Montanari-Richard 14, Hopkins-Shi-Steurer 15)
- Existing frameworks leave incomplete understanding of computational limits.

What are the basic computational limits of random optimization problems?

- Null model MLE is precisely optimization of a **spin glass**:

$$\mathbf{x}^{null} = \arg \max_{\mathbf{x} \in S_N} \langle \mathbf{G}^{(p)}, \mathbf{x}^{\otimes p} \rangle$$

Mean Field Spin Glasses

Polynomials $H_N : \mathbb{R}^N \rightarrow \mathbb{R}$ with **random** coefficients, e.g. random cubic

$$H_N(\sigma) = \frac{1}{N} \sum_{i_1, i_2, i_3=1}^N g_{i_1, i_2, i_3} \cdot \sigma_{i_1} \sigma_{i_2} \sigma_{i_3} \quad g_{i_1, i_2, i_3} \underset{\text{i.i.d.}}{\sim} \mathcal{N}(0, 1)$$

Mean Field Spin Glasses

Polynomials $H_N : \mathbb{R}^N \rightarrow \mathbb{R}$ with **random** coefficients, e.g. random cubic

$$H_N(\sigma) = \frac{1}{N} \sum_{i_1, i_2, i_3=1}^N g_{i_1, i_2, i_3} \cdot \sigma_{i_1} \sigma_{i_2} \sigma_{i_3} = \frac{1}{N} \langle \mathbf{G}^{(3)}, \sigma^{\otimes 3} \rangle \quad g_{i_1, i_2, i_3} \underset{\text{i.i.d.}}{\sim} \mathcal{N}(0, 1)$$

Mean Field Spin Glasses

Polynomials $H_N : \mathbb{R}^N \rightarrow \mathbb{R}$ with **random** coefficients, e.g. random cubic

$$H_N(\sigma) = \frac{1}{N} \sum_{i_1, i_2, i_3=1}^N g_{i_1, i_2, i_3} \cdot \sigma_{i_1} \sigma_{i_2} \sigma_{i_3} = \frac{1}{N} \langle \mathbf{G}^{(3)}, \sigma^{\otimes 3} \rangle \quad g_{i_1, i_2, i_3} \underset{\text{i.i.d.}}{\sim} \mathcal{N}(0, 1)$$

More generally, mix different degrees. For $\gamma_2, \gamma_3, \dots \geq 0$,

$$H_N(\sigma) = \sum_{p=2}^P \frac{\gamma_p}{N^{(p-1)/2}} \langle \mathbf{G}^{(p)}, \sigma^{\otimes p} \rangle \quad \mathbf{G}^{(p)} \in (\mathbb{R}^N)^{\otimes p} \text{ i.i.d. } \mathcal{N}(0, 1)\text{s}$$

Mean Field Spin Glasses

Polynomials $H_N : \mathbb{R}^N \rightarrow \mathbb{R}$ with **random** coefficients, e.g. random cubic

$$H_N(\sigma) = \frac{1}{N} \sum_{i_1, i_2, i_3=1}^N g_{i_1, i_2, i_3} \cdot \sigma_{i_1} \sigma_{i_2} \sigma_{i_3} = \frac{1}{N} \langle \mathbf{G}^{(3)}, \sigma^{\otimes 3} \rangle \quad g_{i_1, i_2, i_3} \underset{\text{i.i.d.}}{\sim} \mathcal{N}(0, 1)$$

More generally, mix different degrees. For $\gamma_2, \gamma_3, \dots \geq 0$,

$$H_N(\sigma) = \sum_{p=2}^P \frac{\gamma_p}{N^{(p-1)/2}} \langle \mathbf{G}^{(p)}, \sigma^{\otimes p} \rangle \quad \mathbf{G}^{(p)} \in (\mathbb{R}^N)^{\otimes p} \text{ i.i.d. } \mathcal{N}(0, 1)\text{s}$$

Gaussian process on \mathbb{R}^N with covariance

$$\mathbb{E}[H_N(\sigma)H_N(\rho)] = N\xi(\langle \sigma, \rho \rangle / N), \quad \xi(q) = \sum_{p=2}^P \gamma_p^2 q^p$$

Mean Field Spin Glasses

Polynomials $H_N : \mathbb{R}^N \rightarrow \mathbb{R}$ with **random** coefficients, e.g. random cubic

$$H_N(\sigma) = \frac{1}{N} \sum_{i_1, i_2, i_3=1}^N g_{i_1, i_2, i_3} \cdot \sigma_{i_1} \sigma_{i_2} \sigma_{i_3} = \frac{1}{N} \langle \mathbf{G}^{(3)}, \sigma^{\otimes 3} \rangle \quad g_{i_1, i_2, i_3} \underset{\text{i.i.d.}}{\sim} \mathcal{N}(0, 1)$$

More generally, mix different degrees. For $\gamma_2, \gamma_3, \dots \geq 0$,

$$H_N(\sigma) = \sum_{p=2}^P \frac{\gamma_p}{N^{(p-1)/2}} \langle \mathbf{G}^{(p)}, \sigma^{\otimes p} \rangle \quad \mathbf{G}^{(p)} \in (\mathbb{R}^N)^{\otimes p} \text{ i.i.d. } \mathcal{N}(0, 1)\text{s}$$

Gaussian process on \mathbb{R}^N with covariance

$$\mathbb{E}[H_N(\sigma)H_N(\rho)] = N\xi(\langle \sigma, \rho \rangle / N), \quad \xi(q) = \sum_{p=2}^P \gamma_p^2 q^p$$

ξ **mixture function**, determines model. Cubic above: $\xi(q) = q^3$

Mean Field Spin Glasses

Polynomials $H_N : \mathbb{R}^N \rightarrow \mathbb{R}$ with **random** coefficients, e.g. random cubic

$$H_N(\sigma) = \frac{1}{N} \sum_{i_1, i_2, i_3=1}^N g_{i_1, i_2, i_3} \cdot \sigma_{i_1} \sigma_{i_2} \sigma_{i_3} = \frac{1}{N} \langle \mathbf{G}^{(3)}, \sigma^{\otimes 3} \rangle \quad g_{i_1, i_2, i_3} \underset{\text{i.i.d.}}{\sim} \mathcal{N}(0, 1)$$

More generally, mix different degrees. For $\gamma_2, \gamma_3, \dots \geq 0$,

$$H_N(\sigma) = \sum_{p=2}^P \frac{\gamma_p}{N^{(p-1)/2}} \langle \mathbf{G}^{(p)}, \sigma^{\otimes p} \rangle \quad \mathbf{G}^{(p)} \in (\mathbb{R}^N)^{\otimes p} \text{ i.i.d. } \mathcal{N}(0, 1)\text{s}$$

Gaussian process on \mathbb{R}^N with covariance

$$\mathbb{E}[H_N(\sigma)H_N(\rho)] = N\xi(\langle \sigma, \rho \rangle / N), \quad \xi(q) = \sum_{p=2}^P \gamma_p^2 q^p$$

ξ **mixture function**, determines model. Cubic above: $\xi(q) = q^3$

Goal: optimize H_N over sphere $S_N = \sqrt{N}\mathbb{S}^{N-1}$

Motivations and Connections

- Origin: diluted magnetic alloys (Sherrington-Kirkpatrick 75)

Motivations and Connections

- Origin: diluted magnetic alloys (Sherrington-Kirkpatrick 75)
- Natural **high-dimensional, non-convex** random optimization problem

Motivations and Connections

- Origin: diluted magnetic alloys (Sherrington-Kirkpatrick 75)
- Natural **high-dimensional, non-convex** random optimization problem
- MLE for tensor PCA log-likelihood in null model (Ben Arous-Mei-Montanari-Nica 17)

Motivations and Connections

- Origin: diluted magnetic alloys (Sherrington-Kirkpatrick 75)
- Natural **high-dimensional, non-convex** random optimization problem
- MLE for tensor PCA log-likelihood in null model (Ben Arous-Mei-Montanari-Nica 17)
- Random MaxCut and MaxSAT with many constraints (Dembo-Montanari-Sen 17, Panchenko 18)

Motivations and Connections

- Origin: diluted magnetic alloys (Sherrington-Kirkpatrick 75)
- Natural **high-dimensional, non-convex** random optimization problem
- MLE for tensor PCA log-likelihood in null model (Ben Arous-Mei-Montanari-Nica 17)
- Random MaxCut and MaxSAT with many constraints (Dembo-Montanari-Sen 17, Panchenko 18)
- Neural networks, high-dimensional statistics (Hopfield 82, Gardner-Derrida 87/88, Talagrand 00/02, Choromanska-Henaff-Mathieu-Ben Arous-LeCun 15, Ding-Sun 18, Fan-Mei-Montanari 21)

The maximum of H_N

Two basic questions for any random optimization problem:

- OPT: maximum value that **exists**?
- ALG: maximum value found by **efficient algorithm**?

The maximum of H_N

Two basic questions for any random optimization problem:

- OPT: maximum value that **exists**?
- ALG: maximum value found by **efficient algorithm**?

Theorem (Parisi 82, Talagrand 06/10, Panchenko 14, Auffinger-Chen 17)

The limiting maximum value

$$\text{OPT} = \text{p-lim}_{N \rightarrow \infty} \frac{1}{N} \max_{\sigma \in S_N} H_N(\sigma)$$

*exists and is given by the **Parisi formula** $P(\xi)$.*

Efficient Optimization

- Today's goal: understand power of **efficient** algorithms \mathcal{A} to optimize H_N . For $\sigma = \mathcal{A}(H_N)$, what is max of

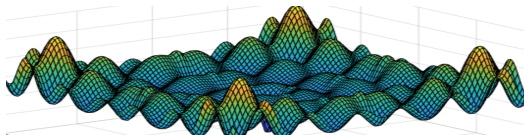
$$E = \frac{1}{N} H_N(\sigma) ?$$

Efficient Optimization

- Today's goal: understand power of **efficient** algorithms \mathcal{A} to optimize H_N . For $\sigma = \mathcal{A}(H_N)$, what is max of

$$E = \frac{1}{N} H_N(\sigma) ?$$

- Gradient descent, convex optimization don't cut it 😞
 - Rich landscapes, e^{cN} bad local maxima well below OPT (ABAČ 13, Subag 17)

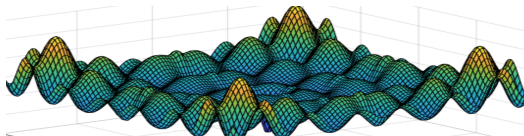


Efficient Optimization

- Today's goal: understand power of **efficient** algorithms \mathcal{A} to optimize H_N . For $\sigma = \mathcal{A}(H_N)$, what is max of

$$E = \frac{1}{N} H_N(\sigma) ?$$

- Gradient descent, convex optimization don't cut it 😞
 - Rich landscapes, e^{cN} bad local maxima well below OPT (ABAČ 13, Subag 17)



- Worst-case lower bounds overly pessimistic 😞
 - Adversarial H_N : $(\log^c N)$ -approximation NP-hard (ABHKS 05, BBHKSZ 12)

Efficient Optimization: Some Approaches

Can study specific algorithms like **Langevin/Glauber dynamics**

Efficient Optimization: Some Approaches

Can study specific algorithms like **Langevin/Glauber dynamics**

- **Rich literature** (Cugliandolo-Kurchen 92, Ben Arous-Dembo-Guionnet 01& 06, Ben Arous-Gheissari-Jagannath 20)
- **Slow mixing, stuck at threshold energy on short time scales**

Efficient Optimization: Some Approaches

Can study specific algorithms like **Langevin/Glauber dynamics**

- **Rich literature** (Cugliandolo-Kurchen 92, Ben Arous-Dembo-Guionnet 01& 06, Ben Arous-Gheissari-Jagannath 20)
- **Slow mixing, stuck at threshold energy on short time scales**

Can study **critical points** of H_N

Efficient Optimization: Some Approaches

Can study specific algorithms like **Langevin/Glauber dynamics**

- **Rich literature** (Cugliandolo-Kurchen 92, Ben Arous-Dembo-Guionnet 01& 06, Ben Arous-Gheissari-Jagannath 20)
- Slow mixing, stuck at threshold energy on short time scales

Can study **critical points** of H_N

- Pure p -spin models ($p \geq 3$): e^{cN} local maxima appear at value $E_\infty < \text{OPT}$ (Auffinger-Ben Arous-Černý 13, Subag 17)
- Conjectured to obstruct e.g. gradient descent
- But no rigorous hardness implications

Informal Result

We determine sharp threshold ALG for a class of **Lipschitz** algorithms

- A Lipschitz algorithm attains ALG
- No Lipschitz algorithm surpasses ALG
- No **known** efficient algorithm surpasses ALG

Informal Result

We determine sharp threshold ALG for a class of **Lipschitz** algorithms

- A Lipschitz algorithm attains ALG
- No Lipschitz algorithm surpasses ALG
- No **known** efficient algorithm surpasses ALG

Result holds for yet more general **multi-species spin glasses**

Overlap Gap Property



solution geometry **clustering** \Rightarrow rigorous hardness for **stable** algorithms

Overlap Gap Property



solution geometry **clustering** \Rightarrow rigorous hardness for **stable** algorithms

- Max independent set in random sparse graphs (Gamarnik-Sudan 14, Rahman-Virág 17, Gamarnik-Jagannath-Wein 20, Wein 20)
- Random (NAE-) k -SAT (Gamarnik-Sudan 17, Bresler-Huang 21)
- Hypergraph maxcut (Chen-Gamarnik-Panchenko-Rahman 19)
- Symmetric binary perceptron (Gamarnik-Kızıldağ-Perkins-Xu 22)
- Mean field spin glass (Gamarnik-Jagannath 19, Gamarnik-Jagannath-Wein 20)

Overlap Gap Property



solution geometry **clustering** \Rightarrow rigorous hardness for **stable** algorithms

- Max independent set in random sparse graphs (Gamarnik-Sudan 14, Rahman-Virág 17, Gamarnik-Jagannath-Wein 20, Wein 20)
- Random (NAE-)k-SAT (Gamarnik-Sudan 17, Bresler-Huang 21)
- Hypergraph maxcut (Chen-Gamarnik-Panchenko-Rahman 19)
- Symmetric binary perceptron (Gamarnik-Kızıldağ-Perkins-Xu 22)
- Mean field spin glass (Gamarnik-Jagannath 19, Gamarnik-Jagannath-Wein 20)

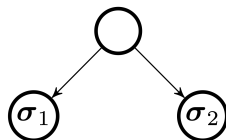
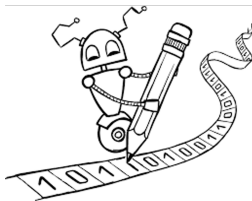
Overlap: $\langle \sigma, \rho \rangle / N \in [-1, 1]$

Overlap gap: no high-value σ, ρ have **medium** overlap $\in [\nu_1, \nu_2]$

- Means high-value points are either close together or far apart

Classic OGP (Gamarnik-Sudan 14)

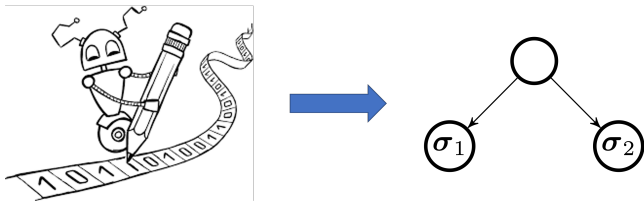
- 1 Stable algorithm \mathcal{A} reaching $E \Rightarrow 2$ points of value E with **medium overlap**



Construct by partially rerandomizing \mathcal{A}

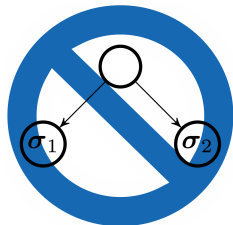
Classic OGP (Gamarnik-Sudan 14)

- 1 Stable algorithm \mathcal{A} reaching $E \Rightarrow 2$ points of value E with **medium overlap**

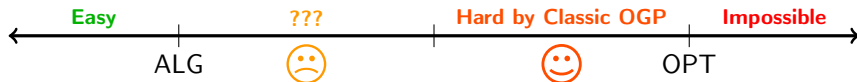


Construct by partially rerandomizing \mathcal{A}

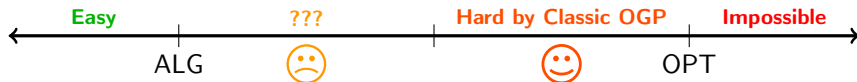
- 2 **Overlap gap** \Rightarrow this pair does not exist. So \mathcal{A} cannot reach E



Classic OGP to Multi-OGP



Classic OGP to Multi-OGP



Multi-OGP: more complex forbidden structure

Classic OGP to Multi-OGP



Multi-OGP: more complex forbidden structure

Classic OGP to Multi-OGP



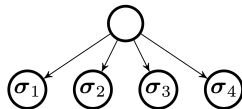
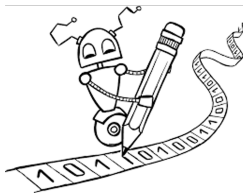
Multi-OGP: more complex forbidden structure

Can we push hardness all the way to ALG?

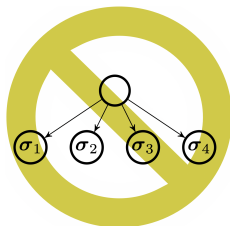
Star OGP (Rahman-Virág 17)

For max independent set

- 1 Stable algorithm \mathcal{A} reaching $E \Rightarrow$ constellation of points of value E



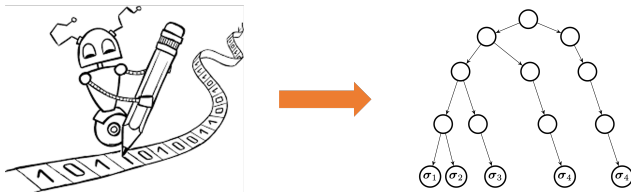
- 2 Such a constellation does not exist. So \mathcal{A} cannot reach E



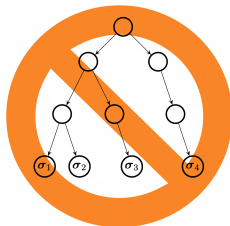
Ladder OGP (Wein 20, Bresler-Huang 21)

For max independent set, random k -SAT

- 1 Stable algorithm \mathcal{A} reaching $E \Rightarrow$ constellation of points of value E



- 2 Such a constellation does not exist. So \mathcal{A} cannot reach E

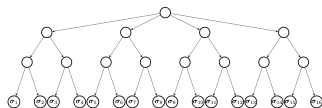


Overview of Main Result (Huang-S 21, 23+)

- We show that for spin glasses, **Branching OGP** gives tight hardness
 - Matches value ALG of best algorithm

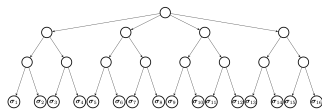
Overview of Main Result (Huang-S 21, 23+)

- We show that for spin glasses, **Branching OGP** gives tight hardness
 - Matches value ALG of best algorithm
- Forbidden constellation is **densely branching ultrametric tree**
 - Inspired by ultrametricity of Gibbs measures $e^{\beta H_N(\mathbf{x})} d\mathbf{x}$ (Parisi 82, Panchenko 14, Jagannath 17, Chatterjee-Slooman 21)



Overview of Main Result (Huang-S 21, 23+)

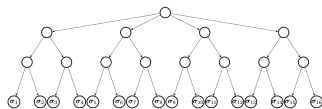
- We show that for spin glasses, **Branching OGP** gives tight hardness
 - Matches value ALG of best algorithm
- Forbidden constellation is **densely branching ultrametric tree**
 - Inspired by ultrametricity of Gibbs measures $e^{\beta H_N(\mathbf{x})} d\mathbf{x}$ (Parisi 82, Panchenko 14, Jagannath 17, Chatterjee-Slooman 21)



- Hardness for $O(1)$ -**Lipschitz** algorithms
 - View \mathcal{A} as map from $(g_{1,1}, \dots, g_{N,N}, g_{1,1,1}, \dots)$ to \mathbb{R}^N (with L^2 distance)

Overview of Main Result (Huang-S 21, 23+)

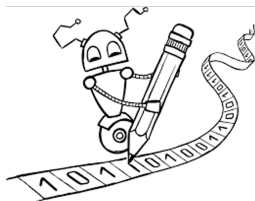
- We show that for spin glasses, **Branching OGP** gives tight hardness
 - Matches value ALG of best algorithm
- Forbidden constellation is **densely branching ultrametric tree**
 - Inspired by ultrametricity of Gibbs measures $e^{\beta H_N(\mathbf{x})} d\mathbf{x}$ (Parisi 82, Panchenko 14, Jagannath 17, Chatterjee-Slooman 21)



- Hardness for $O(1)$ -**Lipschitz** algorithms
 - View \mathcal{A} as map from $(g_{1,1}, \dots, g_{N,N}, g_{1,1,1}, \dots)$ to \mathbb{R}^N (with L^2 distance)
 - Includes:
 - $O(1)$ rounds of gradient descent or any constant order method
 - Langevin dynamics for $e^{\beta H_N}$ for $O(1)$ time
 - The algorithm attaining ALG

Branching OGP (Huang-S 21)

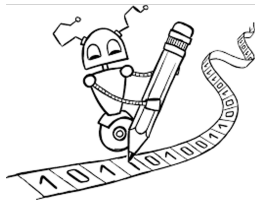
- 1 $O(1)$ -Lipschitz algorithm \mathcal{A} reaching $E \Rightarrow$ ultrametric of points of value E



Construct from correlated Hamiltonian ensemble (more later)

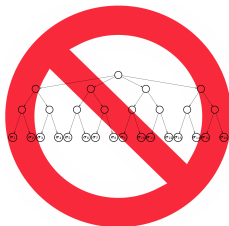
Branching OGP (Huang-S 21)

- 1 $O(1)$ -Lipschitz algorithm \mathcal{A} reaching $E \Rightarrow$ ultrametric of points of value E



Construct from correlated Hamiltonian ensemble (more later)

- 2 Constellation does not exist for $E = \text{ALG} + \varepsilon$. So \mathcal{A} cannot beat ALG



The Algorithmic Threshold

Theorem (Subag 18)

An efficient algorithm finds σ such that

$$\frac{1}{N} H_N(\sigma) \geq \text{ALG} \equiv \int_0^1 \xi''(q)^{1/2} dq.$$

The Algorithmic Threshold

Theorem (Subag 18)

An efficient algorithm finds σ such that

$$\frac{1}{N} H_N(\sigma) \geq \text{ALG} \equiv \int_0^1 \xi''(q)^{1/2} dq.$$

Theorem (Huang-S 21)

If ξ **even**, no $O(1)$ -Lipschitz algorithm beats ALG with probability e^{-cN} .

Tight answer for even models, but brittle proof using **Guerra's interpolation**

The Algorithmic Threshold

Theorem (Subag 18)

An efficient algorithm finds σ such that

$$\frac{1}{N} H_N(\sigma) \geq \text{ALG} \equiv \int_0^1 \xi''(q)^{1/2} dq.$$

Theorem (Huang-S 21)

If ξ **even**, no $O(1)$ -Lipschitz algorithm beats ALG with probability e^{-cN} .

Tight answer for even models, but brittle proof using **Guerra's interpolation**

Theorem (Huang-S 23+)

For **all** ξ , no $O(1)$ -Lipschitz algorithm beats ALG with probability e^{-cN} .

- New proof avoids Guerra's interpolation

The Algorithmic Threshold

Theorem (Subag 18)

An efficient algorithm finds σ such that

$$\frac{1}{N} H_N(\sigma) \geq \text{ALG} \equiv \int_0^1 \xi''(q)^{1/2} dq.$$

Theorem (Huang-S 21)

If ξ **even**, no $O(1)$ -Lipschitz algorithm beats ALG with probability e^{-cN} .

Tight answer for even models, but brittle proof using **Guerra's interpolation**

Theorem (Huang-S 23+)

For **all** ξ , no $O(1)$ -Lipschitz algorithm beats ALG with probability e^{-cN} .

- New proof avoids Guerra's interpolation
- Same method works for multi-species spin glasses (described later)
 - In these models, OPT not always known! (Because Guerra's interpolation fails)

Subag's Algorithm (Hessian Ascent)

For $\delta = 1/D$ constant, $\mathbf{x}^0 = \mathbf{0} \in \mathbb{R}^N$:

Subag's Algorithm (Hessian Ascent)

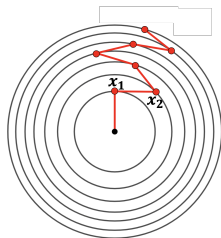
For $\delta = 1/D$ constant, $\mathbf{x}^0 = \mathbf{0} \in \mathbb{R}^N$:

- 1 Take \mathbf{v}^t the top eigenvector of tangential Hessian $\nabla^2 H_N(\mathbf{x}^t)|_{(\mathbf{x}^t)^\perp}$

Subag's Algorithm (Hessian Ascent)

For $\delta = 1/D$ constant, $\mathbf{x}^0 = \mathbf{0} \in \mathbb{R}^N$:

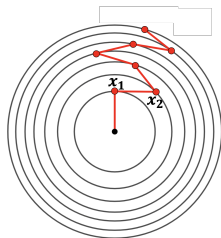
- 1 Take \mathbf{v}^t the top eigenvector of tangential Hessian $\nabla^2 H_N(\mathbf{x}^t)|_{(\mathbf{x}^t)^\perp}$
- 2 Explore with small orthogonal steps: $\mathbf{x}^{t+1} = \mathbf{x}^t \pm \sqrt{\delta N} \mathbf{v}^t$.
(Since $\mathbf{v}^t \perp \mathbf{x}^t$, we have $\|\mathbf{x}^t\|_2^2 = t\delta N$)



Subag's Algorithm (Hessian Ascent)

For $\delta = 1/D$ constant, $\mathbf{x}^0 = \mathbf{0} \in \mathbb{R}^N$:

- 1 Take \mathbf{v}^t the top eigenvector of tangential Hessian $\nabla^2 H_N(\mathbf{x}^t)|_{(\mathbf{x}^t)^\perp}$
- 2 Explore with small orthogonal steps: $\mathbf{x}^{t+1} = \mathbf{x}^t \pm \sqrt{\delta N} \mathbf{v}^t$.
(Since $\mathbf{v}^t \perp \mathbf{x}^t$, we have $\|\mathbf{x}^t\|_2^2 = t\delta N$)

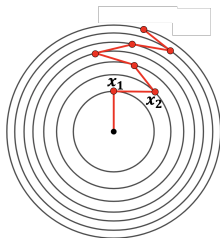


- 3 Output $\sigma = \mathbf{x}^D \in S_N$

Subag's Algorithm (Hessian Ascent)

For $\delta = 1/D$ constant, $\mathbf{x}^0 = \mathbf{0} \in \mathbb{R}^N$:

- 1 Take \mathbf{v}^t the top eigenvector of tangential Hessian $\nabla^2 H_N(\mathbf{x}^t)|_{(\mathbf{x}^t)^\perp}$
- 2 Explore with small orthogonal steps: $\mathbf{x}^{t+1} = \mathbf{x}^t \pm \sqrt{\delta N} \mathbf{v}^t$.
(Since $\mathbf{v}^t \perp \mathbf{x}^t$, we have $\|\mathbf{x}^t\|_2^2 = t\delta N$)



- 3 Output $\sigma = \mathbf{x}^D \in S_N$

Can be implemented as $O(1)$ -Lipschitz algorithm (El Alaoui-Montanari-Sellke 20)

Analysis of Subag's Algorithm

- If $\|\mathbf{x}\|_2 = \sqrt{qN}$, tangential Hessian $\nabla^2 H_N(\mathbf{x})_{\mathbf{x}^\perp}$ has law $\xi''(q)^{1/2} \times GOE_{N-1}$

Analysis of Subag's Algorithm

- If $\|\mathbf{x}\|_2 = \sqrt{qN}$, tangential Hessian $\nabla^2 H_N(\mathbf{x})_{\mathbf{x}^\perp}$ has law $\xi''(q)^{1/2} \times GOE_{N-1}$
- $\lambda_{\max}(GOE) \approx 2$, so step t gains

$$\frac{H_N(\mathbf{x}^{t+1}) - H_N(\mathbf{x}^t)}{N} \approx \delta \xi''(t\delta)^{1/2}$$

Analysis of Subag's Algorithm

- If $\|\mathbf{x}\|_2 = \sqrt{qN}$, tangential Hessian $\nabla^2 H_N(\mathbf{x})_{\mathbf{x}^\perp}$ has law $\xi''(q)^{1/2} \times GOE_{N-1}$
- $\lambda_{\max}(GOE) \approx 2$, so step t gains

$$\frac{H_N(\mathbf{x}^{t+1}) - H_N(\mathbf{x}^t)}{N} \approx \delta \xi''(t\delta)^{1/2}$$

- Summing over $t = 1, \dots, D$ and taking $\delta \rightarrow 0$,

$$\frac{1}{N} H_N(\mathbf{x}^D) \approx \int_0^1 \xi''(q)^{1/2} dq = \text{ALG}$$

Analysis of Subag's Algorithm

- If $\|\mathbf{x}\|_2 = \sqrt{qN}$, tangential Hessian $\nabla^2 H_N(\mathbf{x})_{\mathbf{x}^\perp}$ has law $\xi''(q)^{1/2} \times GOE_{N-1}$
- $\lambda_{\max}(GOE) \approx 2$, so step t gains

$$\frac{H_N(\mathbf{x}^{t+1}) - H_N(\mathbf{x}^t)}{N} \approx \delta \xi''(t\delta)^{1/2}$$

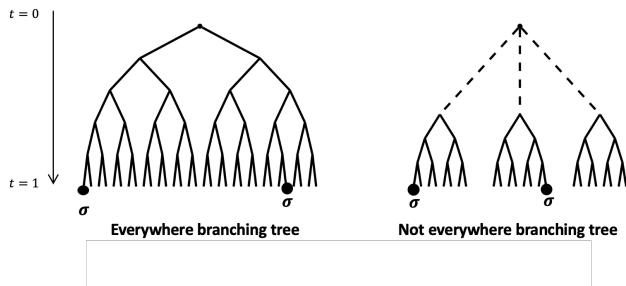
- Summing over $t = 1, \dots, D$ and taking $\delta \rightarrow 0$,

$$\frac{1}{N} H_N(\mathbf{x}^D) \approx \int_0^1 \xi''(q)^{1/2} dq = \text{ALG}$$

- Although \mathbf{x}^t depends on H_N , ok by **uniform** lower bound on $\lambda_{\min}(H_N(\mathbf{x})_{\mathbf{x}^\perp})$ for all $\|\mathbf{x}\|_2 = \sqrt{qN}$

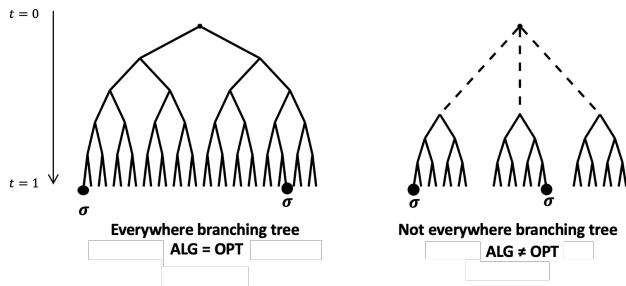
Connection to Physics Theory

- Approximate maxima of H_N are **ultrametric**, i.e. isometric to a tree



Connection to Physics Theory

- Approximate maxima of H_N are **ultrametric**, i.e. isometric to a tree

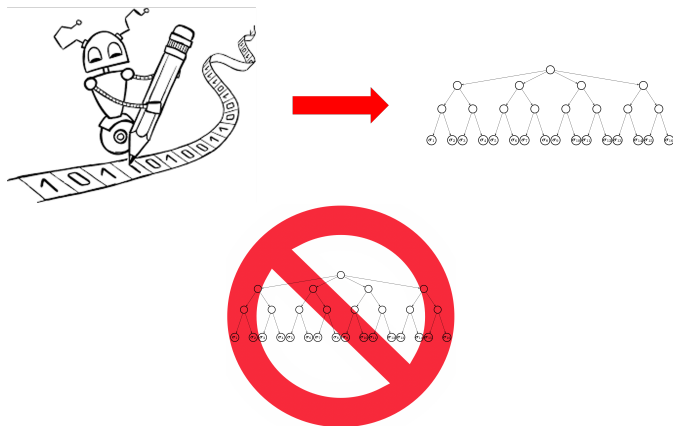


Subag's algorithm attains OPT iff branching occurs at all depths

- Intuition: algorithm traces root-to-leaf path of tree

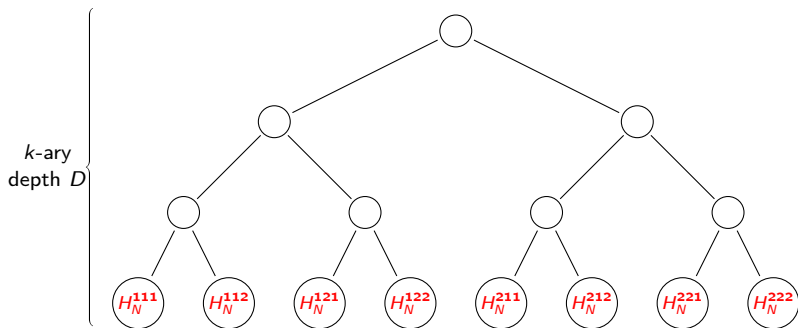
Branching OGP

Subag's algorithm reaches ALG. We next see how to show hardness beyond ALG



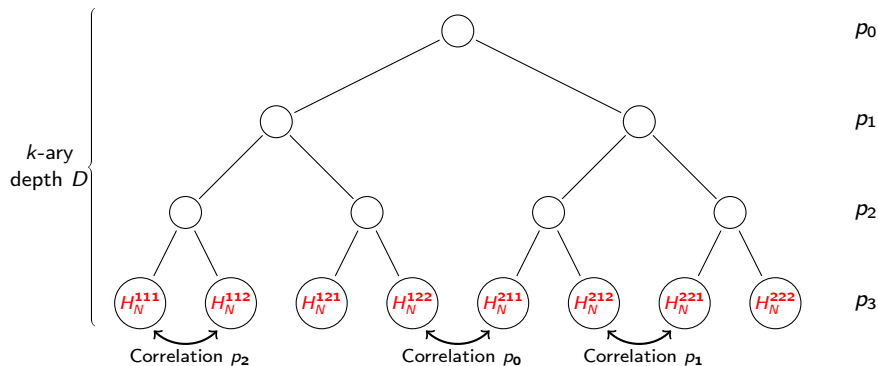
Hierarchically Correlated Hamiltonians

Generate tree of Hamiltonians $(H_N^u)_{u \in [k]^D}$



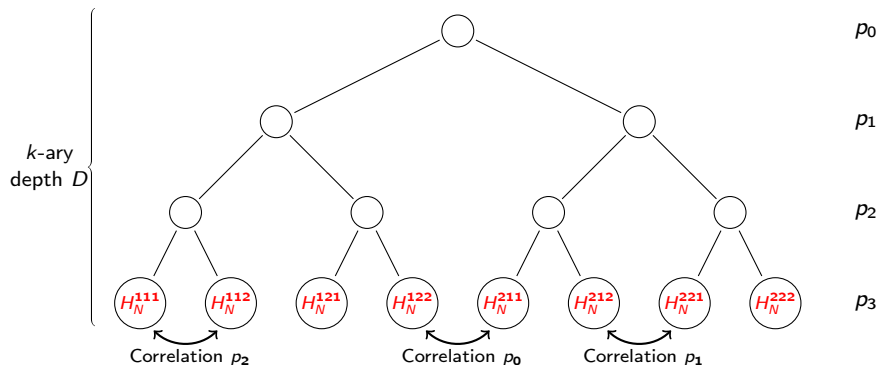
Hierarchically Correlated Hamiltonians

Generate tree of Hamiltonians $(H_N^u)_{u \in [k]^D}$



Hierarchically Correlated Hamiltonians

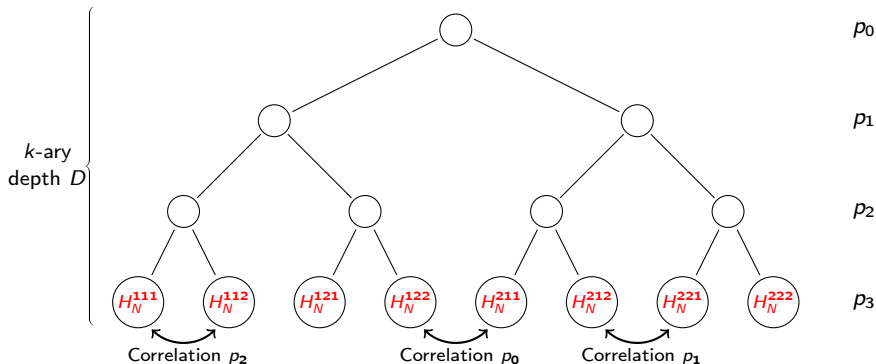
Generate tree of Hamiltonians $(H_N^u)_{u \in [k]^D}$



$$k, D \in \mathbb{N} \text{ large, } 0 \leq p_0 < p_1 < \dots < p_D = 1$$

Hierarchically Correlated Hamiltonians

Generate tree of Hamiltonians $(H_N^u)_{u \in [k]^D}$

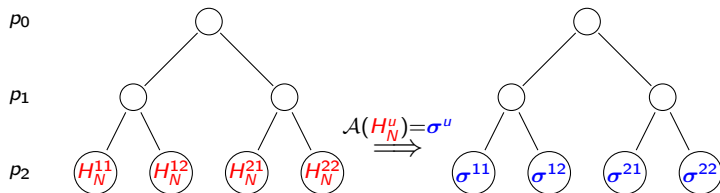


$$k, D \in \mathbb{N} \text{ large, } 0 \leq p_0 < p_1 < \dots < p_D = 1$$

Vocab: " $(H_N^u)_{u \in [k]^D}$ has correlation $\vec{p} = (p_0, \dots, p_D)$ "

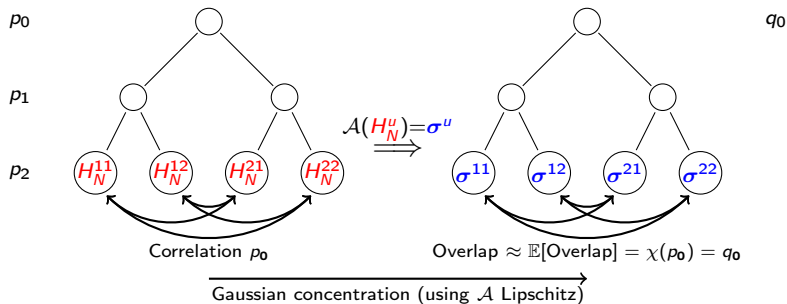
Lipschitz Algorithms to Ultrametric Trees

Let \mathcal{A} be $O(1)$ -Lipschitz



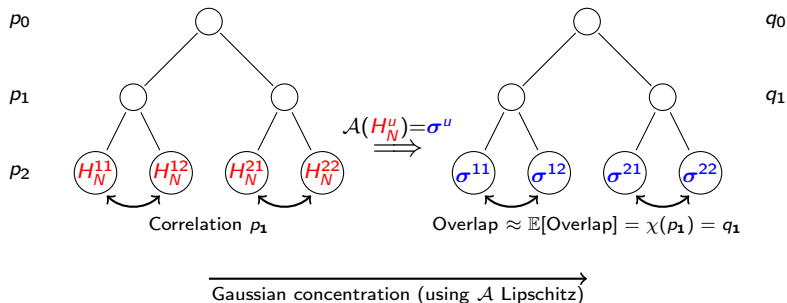
Lipschitz Algorithms to Ultrametric Trees

Let \mathcal{A} be $O(1)$ -Lipschitz



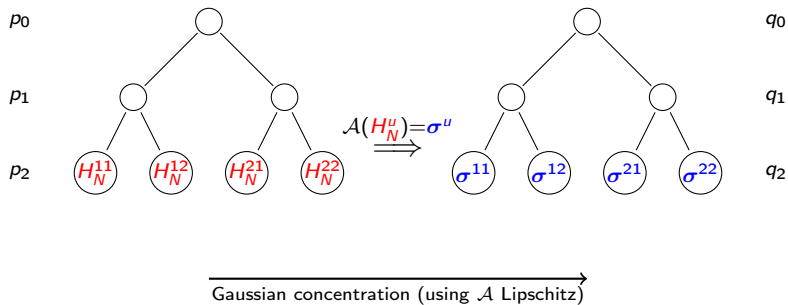
Lipschitz Algorithms to Ultrametric Trees

Let \mathcal{A} be $O(1)$ -Lipschitz



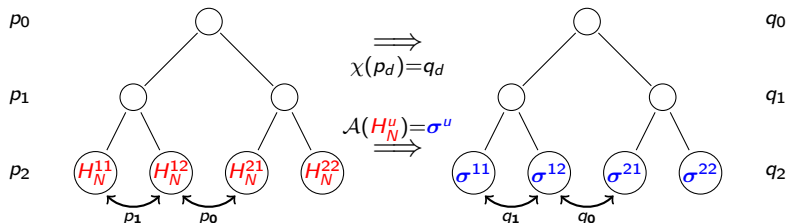
Lipschitz Algorithms to Ultrametric Trees

Let \mathcal{A} be $O(1)$ -Lipschitz



Lipschitz Algorithms to Ultrametric Trees

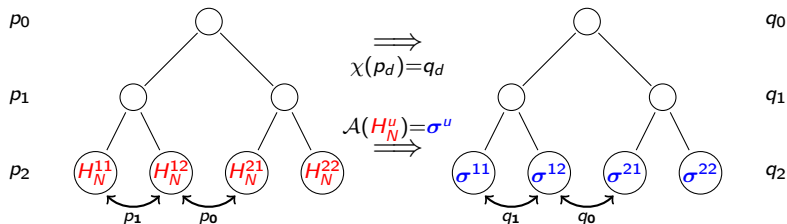
Let \mathcal{A} be $O(1)$ -Lipschitz



$\xrightarrow{\text{Gaussian concentration (using } \mathcal{A} \text{ Lipschitz)}}$
 $(\sigma^u)_{u \in [k]^D}$ is approximately ultrametric

Lipschitz Algorithms to Ultrametric Trees

Let \mathcal{A} be $O(1)$ -Lipschitz



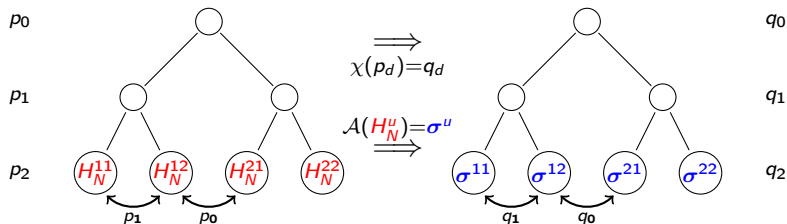
Gaussian concentration (using \mathcal{A} Lipschitz)

$(\sigma^u)_{u \in [k]^D}$ is approximately ultrametric

Vocab: " $(\sigma^u)_{u \in [k]^D}$ has geometry $\vec{q} = (q_0, \dots, q_D)$ "

Lipschitz Algorithms to Ultrametric Trees

Let \mathcal{A} be $O(1)$ -Lipschitz



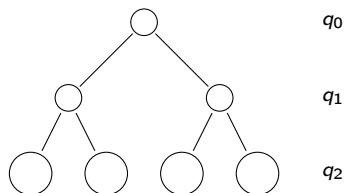
Gaussian concentration (using \mathcal{A} Lipschitz)

$(\sigma^u)_{u \in [k]^D}$ is approximately ultrametric

Vocab: " $(\sigma^u)_{u \in [k]^D}$ has geometry $\vec{q} = (q_0, \dots, q_D)$ "

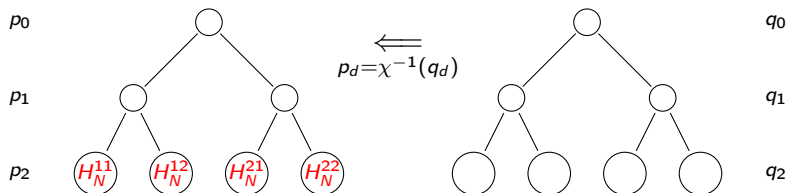
χ continuous. Can choose \vec{p} to achieve **any** $0 \leq q_0 < \dots < q_D = 1$

Lipschitz Algorithms to Ultrametric Trees



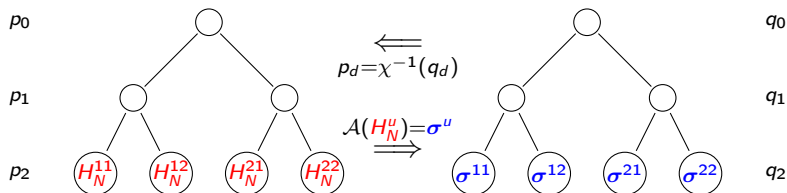
- Suppose Lipschitz \mathcal{A} reaches E . Then, for any target \vec{q} ,

Lipschitz Algorithms to Ultrametric Trees



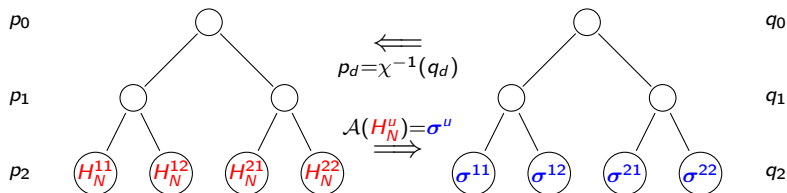
- Suppose Lipschitz \mathcal{A} reaches E . Then, for any target \vec{q} ,
- Exists \vec{p}

Lipschitz Algorithms to Ultrametric Trees



- Suppose Lipschitz \mathcal{A} reaches E . Then, for any target \vec{q} ,
- Exists \vec{p} and $(\sigma^u)_{u \in [k]^D}$ with geometry \vec{q} , so that

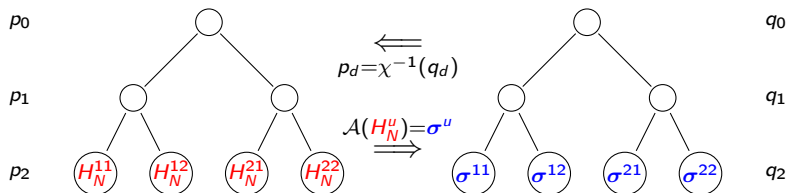
Lipschitz Algorithms to Ultrametric Trees



- Suppose Lipschitz \mathcal{A} reaches E . Then, for any target \vec{q} ,
- Exists \vec{p} and $(\sigma^u)_{u \in [k]^D}$ with geometry \vec{q} , so that

$$\frac{1}{N} H_N^u(\sigma^u) \geq E \quad \text{for all } u \in [k]^D$$

Lipschitz Algorithms to Ultrametric Trees

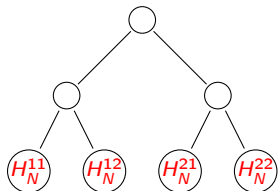


- Suppose Lipschitz \mathcal{A} reaches E . Then, for any target \vec{q} ,
- Exists \vec{p} and $(\sigma^u)_{u \in [k]^D}$ with geometry \vec{q} , so that

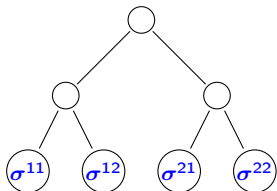
$$\frac{1}{N} H_N^u(\sigma^u) \geq E \quad \text{for all } u \in [k]^D$$

- For **some** \vec{p} , there is a tree constellation with value E and geometry \vec{q}

The value BOGP

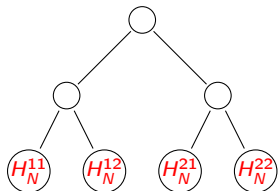


Correlations $\vec{p} = (p_0, \dots, p_D)$

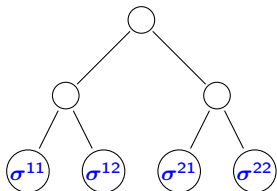


Geometry $\vec{q} = (q_0, \dots, q_D) = (0, \delta, \dots, 1)$
 $\delta = 1/D$

The value BOGP



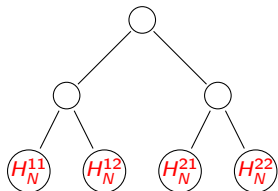
Correlations $\vec{p} = (p_0, \dots, p_D)$



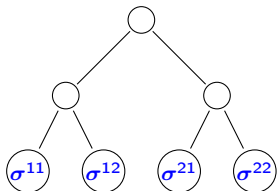
Geometry $\vec{q} = (q_0, \dots, q_D) = (0, \delta, \dots, 1)$
 $\delta = 1/D$

$$\text{TreeValue}(\vec{p}) = \text{p-lim}_{N \rightarrow \infty} \max_{\substack{(\sigma^u)_{u \in [k]^D} \\ \text{geometry } \vec{q}}} \frac{1}{k^D} \sum_{u \in [k]^D} \frac{1}{N} H_N^u(\sigma^u)$$

The value BOGP



Correlations $\vec{p} = (p_0, \dots, p_D)$

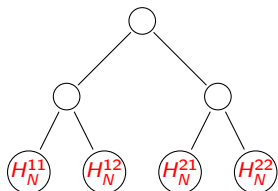


Geometry $\vec{q} = (q_0, \dots, q_D) = (0, \delta, \dots, 1)$
 $\delta = 1/D$

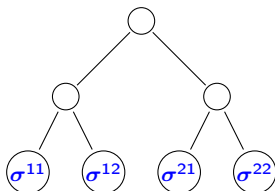
$$\text{TreeValue}(\vec{p}) = \text{p-lim}_{N \rightarrow \infty} \max_{\substack{(\sigma^u)_{u \in [k]^D} \\ \text{geometry } \vec{q}}} \frac{1}{k^D} \sum_{u \in [k]^D} \frac{1}{N} H_N^u(\sigma^u)$$

$$\text{BOGP} = \max_{\vec{p}} \text{TreeValue}(\vec{p})$$

The value BOGP



Correlations $\vec{p} = (p_0, \dots, p_D)$



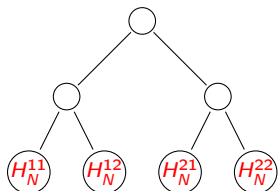
Geometry $\vec{q} = (q_0, \dots, q_D) = (0, \delta, \dots, 1)$
 $\delta = 1/D$

$$\text{TreeValue}(\vec{p}) = \text{p-lim}_{N \rightarrow \infty} \max_{\substack{(\sigma^u)_{u \in [k]^D} \\ \text{geometry } \vec{q}}} \frac{1}{k^D} \sum_{u \in [k]^D} \frac{1}{N} H_N^u(\sigma^u)$$

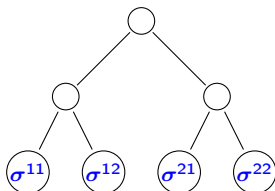
$$\text{BOGP} = \max_{\vec{p}} \text{TreeValue}(\vec{p})$$

- For **any** \vec{p} , there is **no** tree constellation with value $\text{BOGP} + \varepsilon$ and geometry \vec{q}

The value BOGP



Correlations $\vec{p} = (p_0, \dots, p_D)$



Geometry $\vec{q} = (q_0, \dots, q_D) = (0, \delta, \dots, 1)$
 $\delta = 1/D$

$$\text{TreeValue}(\vec{p}) = \text{p-lim}_{N \rightarrow \infty} \max_{\substack{(\sigma^u)_{u \in [k]^D} \\ \text{geometry } \vec{q}}} \frac{1}{k^D} \sum_{u \in [k]^D} \frac{1}{N} H_N^u(\sigma^u)$$

$$\text{BOGP} = \max_{\vec{p}} \text{TreeValue}(\vec{p})$$

- For **any** \vec{p} , there is **no** tree constellation with value $\text{BOGP} + \varepsilon$ and geometry \vec{q}
- \Rightarrow No $O(1)$ -Lipschitz algorithm attains $\text{BOGP} + \varepsilon$

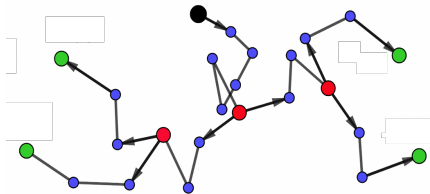
New Proof Idea: Greedy is Best

Remains to upper bound BOGP (by ALG)

New Proof Idea: Greedy is Best

Remains to upper bound BOGP (by ALG)

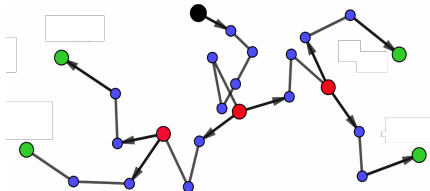
- Can **branch** Subag's algorithm by taking top k eigenvectors
- This is a multi-valued algorithm. All outputs \approx ALG by same analysis



New Proof Idea: Greedy is Best

Remains to upper bound BOGP (by ALG)

- Can **branch** Subag's algorithm by taking top k eigenvectors
- This is a multi-valued algorithm. All outputs \approx ALG by same analysis

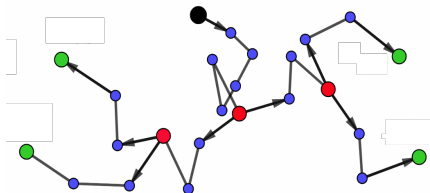


- This tree is built in a greedy way

New Proof Idea: Greedy is Best

Remains to upper bound BOGP (by ALG)

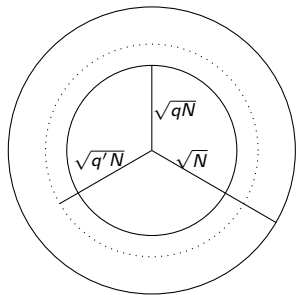
- Can **branch** Subag's algorithm by taking top k eigenvectors
- This is a multi-valued algorithm. All outputs \approx ALG by same analysis



- This tree is built in a greedy way
- Main claim: best way to construct tree is greedy
 - "Can't plan ahead so that my gain at 20th level is unusually big"
 - Proved by **uniform concentration**

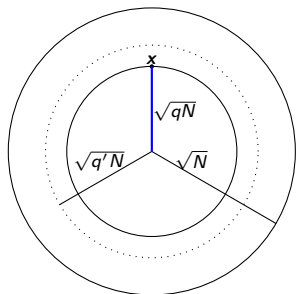
Uniform Concentration

Configuration $\mathbf{x}, \mathbf{x}^1, \dots, \mathbf{x}^k$:



Uniform Concentration

Configuration $\mathbf{x}, \mathbf{x}^1, \dots, \mathbf{x}^k$:

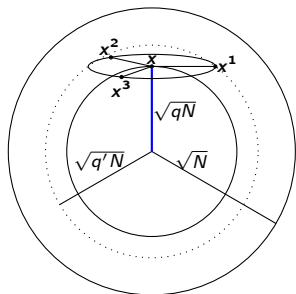


Radius:

$$\|\mathbf{x}\|_2 = \sqrt{qN}$$

Uniform Concentration

Configuration $\mathbf{x}, \mathbf{x}^1, \dots, \mathbf{x}^k$:



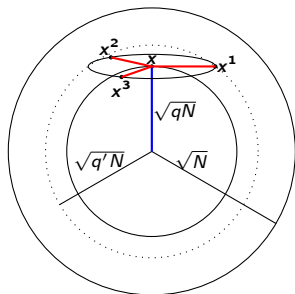
Radius:

$$\|\mathbf{x}\|_2 = \sqrt{qN}$$

$$\|\mathbf{x}^i\|_2 = \sqrt{q'N}$$

Uniform Concentration

Configuration $\mathbf{x}, \mathbf{x}^1, \dots, \mathbf{x}^k$:



Radius:

$$\|\mathbf{x}\|_2 = \sqrt{qN}$$

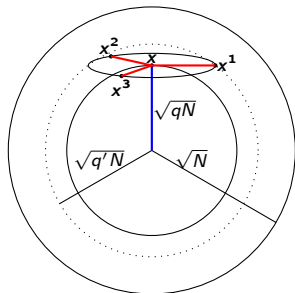
$$\|\mathbf{x}^i\|_2 = \sqrt{q'N}$$

Increment orthogonality:

$$\mathbf{x}^i - \mathbf{x} \perp \mathbf{x}^j - \mathbf{x} \perp \mathbf{x}$$

Uniform Concentration

Configuration $\mathbf{x}, \mathbf{x}^1, \dots, \mathbf{x}^k$:



$$F(\mathbf{x}) = \max_{\mathbf{x}^1, \dots, \mathbf{x}^k} \frac{1}{kN} \sum_{i=1}^k (H_N(\mathbf{x}^i) - H_N(\mathbf{x}))$$

"Improvement in H_N from \mathbf{x} to its children"

Radius:

$$\|\mathbf{x}\|_2 = \sqrt{qN}$$

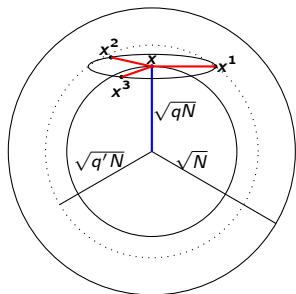
$$\|\mathbf{x}^i\|_2 = \sqrt{q'N}$$

Increment orthogonality:

$$\mathbf{x}^i - \mathbf{x} \perp \mathbf{x}^j - \mathbf{x} \perp \mathbf{x}$$

Uniform Concentration

Configuration $\mathbf{x}, \mathbf{x}^1, \dots, \mathbf{x}^k$:



Radius:

$$\|\mathbf{x}\|_2 = \sqrt{qN}$$

$$\|\mathbf{x}^i\|_2 = \sqrt{q'N}$$

Increment orthogonality:

$$\mathbf{x}^i - \mathbf{x} \perp \mathbf{x}^j - \mathbf{x} \perp \mathbf{x}$$

$$F(\mathbf{x}) = \max_{\mathbf{x}^1, \dots, \mathbf{x}^k} \frac{1}{kN} \sum_{i=1}^k (H_N(\mathbf{x}^i) - H_N(\mathbf{x}))$$

"Improvement in H_N from \mathbf{x} to its children"

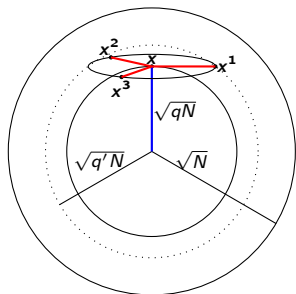
Lemma (Uniform Concentration, cf. Subag 18)

For any $\eta > 0$, for sufficiently large $k \geq k_0(\eta)$,

$$\mathbb{P} \left[|F(\mathbf{x}) - \mathbb{E} F(\mathbf{x})| \leq \eta \quad \forall \|\mathbf{x}\|_2 = \sqrt{qN} \right] \geq 1 - e^{-cN}$$

Uniform Concentration

Configuration $\mathbf{x}, \mathbf{x}^1, \dots, \mathbf{x}^k$:



Radius:

$$\|\mathbf{x}\|_2 = \sqrt{qN}$$

$$\|\mathbf{x}^i\|_2 = \sqrt{q'N}$$

Increment orthogonality:

$$\mathbf{x}^i - \mathbf{x} \perp \mathbf{x}^j - \mathbf{x} \perp \mathbf{x}$$

$$F(\mathbf{x}) = \max_{\mathbf{x}^1, \dots, \mathbf{x}^k} \frac{1}{kN} \sum_{i=1}^k (H_N(\mathbf{x}^i) - H_N(\mathbf{x}))$$

"Improvement in H_N from \mathbf{x} to its children"

Lemma (Uniform Concentration, cf. Subag 18)

For any $\eta > 0$, for sufficiently large $k \geq k_0(\eta)$,

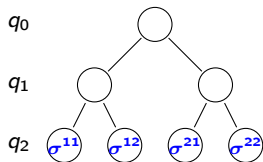
$$\mathbb{P} \left[|F(\mathbf{x}) - \mathbb{E} F(\mathbf{x})| \leq \eta \forall \|\mathbf{x}\|_2 = \sqrt{qN} \right] \geq 1 - e^{-cN}$$

No $\|\mathbf{x}\|_2 = \sqrt{qN}$ is unusually good for building a tree, so might as well be greedy.

Upper Bounding the Tree Value

Let interior σ^u be recursive barycenters:

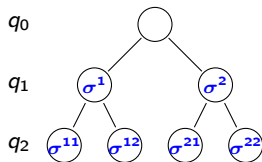
$$\sigma^u = \frac{1}{k} \sum_{i=1}^k \sigma^{ui}$$



Upper Bounding the Tree Value

Let interior σ^u be recursive barycenters:

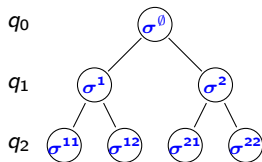
$$\sigma^u = \frac{1}{k} \sum_{i=1}^k \sigma^{ui}$$



Upper Bounding the Tree Value

Let interior σ^u be recursive barycenters:

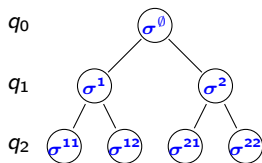
$$\sigma^u = \frac{1}{k} \sum_{i=1}^k \sigma^{ui}$$



Upper Bounding the Tree Value

Let interior σ^u be recursive barycenters:

$$\sigma^u = \frac{1}{k} \sum_{i=1}^k \sigma^{ui}$$



Satisfy orthogonality relations approximately if k large:

$$\|\sigma^u\|_2 \approx \sqrt{q_{|u|}} N$$
$$\sigma^{ui} - \sigma^u \perp \sigma^{uj} - \sigma^u \perp \sigma^u$$

Upper Bounding the Tree Value

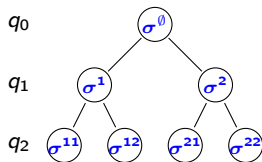
Let interior σ^u be recursive barycenters:

$$\sigma^u = \frac{1}{k} \sum_{i=1}^k \sigma^{ui}$$

Suppose first all H_N^u identical. ($\vec{p} = \vec{1}$)

Want to upper bound tree value:

$$\frac{1}{k^D} \sum_{u \in [k]^D} \frac{1}{N} H_N(\sigma^u)$$



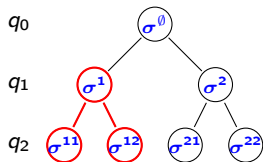
Satisfy orthogonality relations approximately if k large:

$$\|\sigma^u\|_2 \approx \sqrt{q_{|u|} N}$$
$$\sigma^{ui} - \sigma^u \perp \sigma^{uj} - \sigma^u \perp \sigma^u$$

Upper Bounding the Tree Value

Let interior σ^u be recursive barycenters:

$$\sigma^u = \frac{1}{k} \sum_{i=1}^k \sigma^{ui}$$



Satisfy orthogonality relations approximately if k large:

$$\|\sigma^u\|_2 \approx \sqrt{q_{|u|} N}$$

$$\sigma^{ui} - \sigma^u \perp \sigma^{uj} - \sigma^u \perp \sigma^u$$

Suppose first all H_N^u identical. ($\vec{p} = \vec{1}$)
Want to upper bound tree value:

$$\frac{1}{k^D} \sum_{u \in [k]^D} \frac{1}{N} H_N(\sigma^u)$$

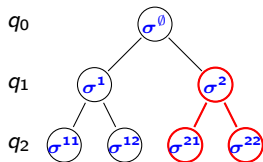
Write as sum of **claw increments**

$$\frac{1}{kN} \sum_{i=1}^k \left(H_N(\sigma^{ui}) - H_N(\sigma^u) \right)$$

Upper Bounding the Tree Value

Let interior σ^u be recursive barycenters:

$$\sigma^u = \frac{1}{k} \sum_{i=1}^k \sigma^{ui}$$



Satisfy orthogonality relations approximately if k large:

$$\|\sigma^u\|_2 \approx \sqrt{q_{|u|} N}$$

$$\sigma^{ui} - \sigma^u \perp \sigma^{uj} - \sigma^u \perp \sigma^u$$

Suppose first all H_N^u identical. ($\vec{p} = \vec{1}$)
Want to upper bound tree value:

$$\frac{1}{k^D} \sum_{u \in [k]^D} \frac{1}{N} H_N(\sigma^u)$$

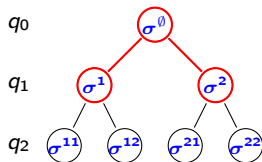
Write as sum of **claw increments**

$$\frac{1}{kN} \sum_{i=1}^k \left(H_N(\sigma^{ui}) - H_N(\sigma^u) \right)$$

Upper Bounding the Tree Value

Let interior σ^u be recursive barycenters:

$$\sigma^u = \frac{1}{k} \sum_{i=1}^k \sigma^{ui}$$



Satisfy orthogonality relations approximately if k large:

$$\|\sigma^u\|_2 \approx \sqrt{q_{|u|} N}$$

$$\sigma^{ui} - \sigma^u \perp \sigma^{uj} - \sigma^u \perp \sigma^u$$

Suppose first all H_N^u identical. ($\vec{p} = \vec{1}$)
Want to upper bound tree value:

$$\frac{1}{k^D} \sum_{u \in [k]^D} \frac{1}{N} H_N(\sigma^u)$$

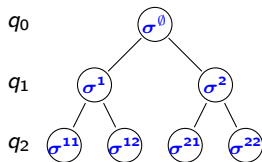
Write as sum of **claw increments**

$$\frac{1}{kN} \sum_{i=1}^k \left(H_N(\sigma^{ui}) - H_N(\sigma^u) \right)$$

Upper Bounding the Tree Value

Let interior σ^u be recursive barycenters:

$$\sigma^u = \frac{1}{k} \sum_{i=1}^k \sigma^{ui}$$



Satisfy orthogonality relations approximately if k large:

$$\|\sigma^u\|_2 \approx \sqrt{q_{|u|} N}$$

$$\sigma^{ui} - \sigma^u \perp \sigma^{uj} - \sigma^u \perp \sigma^u$$

Suppose first all H_N^u identical. ($\vec{p} = \vec{1}$)
Want to upper bound tree value:

$$\frac{1}{k^D} \sum_{u \in [k]^D} \frac{1}{N} H_N(\sigma^u)$$

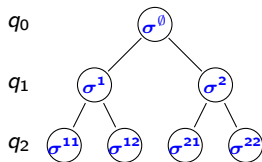
Write as sum of **claw increments**

$$\frac{1}{kN} \sum_{i=1}^k \left(H_N(\sigma^{ui}) - H_N(\sigma^u) \right) \leq F(\sigma^u)$$

Upper Bounding the Tree Value

Let interior σ^u be recursive barycenters:

$$\sigma^u = \frac{1}{k} \sum_{i=1}^k \sigma^{ui}$$



Satisfy orthogonality relations approximately if k large:

$$\|\sigma^u\|_2 \approx \sqrt{q_{|u|} N}$$
$$\sigma^{ui} - \sigma^u \perp \sigma^{uj} - \sigma^u \perp \sigma^u$$

Suppose first all H_N^u identical. ($\vec{p} = \vec{1}$)
Want to upper bound tree value:

$$\frac{1}{k^D} \sum_{u \in [k]^D} \frac{1}{N} H_N(\sigma^u)$$

Write as sum of **claw increments**

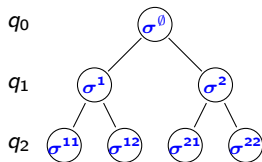
$$\frac{1}{kN} \sum_{i=1}^k \left(H_N(\sigma^{ui}) - H_N(\sigma^u) \right) \leq F(\sigma^u)$$

$F(\sigma^u) \approx \mathbb{E}F(\sigma^u)$ by uniform concentration!

Upper Bounding the Tree Value

Let interior σ^u be recursive barycenters:

$$\sigma^u = \frac{1}{k} \sum_{i=1}^k \sigma^{ui}$$



Satisfy orthogonality relations approximately if k large:

$$\|\sigma^u\|_2 \approx \sqrt{q_{|u|}} N$$

$$\sigma^{ui} - \sigma^u \perp \sigma^{uj} - \sigma^u \perp \sigma^u$$

Suppose first all H_N^u identical. ($\vec{p} = \vec{1}$)
Want to upper bound tree value:

$$\frac{1}{k^D} \sum_{u \in [k]^D} \frac{1}{N} H_N(\sigma^u)$$

Write as sum of **claw increments**

$$\frac{1}{kN} \sum_{i=1}^k \left(H_N(\sigma^{ui}) - H_N(\sigma^u) \right) \leq F(\sigma^u)$$

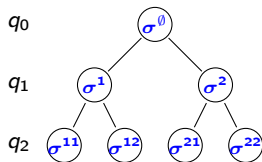
$F(\sigma^u) \approx \mathbb{E}F(\sigma^u)$ by uniform concentration!

Level- d increments match Subag's algorithm

Upper Bounding the Tree Value

Let interior σ^u be recursive barycenters:

$$\sigma^u = \frac{1}{k} \sum_{i=1}^k \sigma^{ui}$$



Satisfy orthogonality relations approximately if k large:

$$\|\sigma^u\|_2 \approx \sqrt{q_{|u|}} N$$

$$\sigma^{ui} - \sigma^u \perp \sigma^{uj} - \sigma^u \perp \sigma^u$$

Suppose first all H_N^u identical. ($\vec{p} = \vec{1}$)
Want to upper bound tree value:

$$\frac{1}{k^D} \sum_{u \in [k]^D} \frac{1}{N} H_N(\sigma^u)$$

Write as sum of **claw increments**

$$\frac{1}{kN} \sum_{i=1}^k \left(H_N(\sigma^{ui}) - H_N(\sigma^u) \right) \leq F(\sigma^u)$$

$F(\sigma^u) \approx \mathbb{E}F(\sigma^u)$ by uniform concentration!

Level- d increments match Subag's algorithm

General \vec{p} : similarly bound

$$\frac{1}{kN} \sum_{i=1}^k \left(H_N^{ui}(\sigma^{ui}) - H_N^u(\sigma^u) \right)$$

Branching OGP is Necessary for Tight Hardness



Branching OGP is Necessary for Tight Hardness



Theorem (Huang-S 21)

If an ultrametric constellation is forbidden at value $ALG + \varepsilon$, it must contain a complete binary subtree of diverging depth as $\varepsilon \rightarrow 0$.

Multi-Species Spin Glasses

- Up to now: polynomials in variables x_1, \dots, x_N that **all look alike**

Multi-Species Spin Glasses

- Up to now: polynomials in variables x_1, \dots, x_N that **all look alike**
- Multi-species models: multiple “variable types” x_i, y_i, z_i, \dots
 - Coefficients of $x_i x_j, x_i y_j, x_i y_j z_k$ have different variances

Multi-Species Spin Glasses

- Up to now: polynomials in variables x_1, \dots, x_N that **all look alike**
- Multi-species models: multiple “variable types” x_i, y_i, z_i, \dots
 - Coefficients of $x_i x_j, x_i y_j, x_i y_j z_k$ have different variances
- Example: **bipartite SK model**

$$H_N(\mathbf{x}, \mathbf{y}) = \frac{1}{\sqrt{N}} \langle \mathbf{G} \mathbf{x}, \mathbf{y} \rangle, \quad \mathbf{G} \in \mathbb{R}^{N \times N} \text{ i.i.d. } \mathcal{N}(0, 1) \text{ entries}$$

or higher-order polynomials

$$H_N(\mathbf{x}, \mathbf{y}) = \frac{1}{N} \langle \mathbf{G}, \mathbf{x}^{\otimes 3} \rangle + \frac{1}{N} \langle \mathbf{G}', \mathbf{x} \otimes \mathbf{y}^{\otimes 2} \rangle, \quad \mathbf{G}, \mathbf{G}' \in (\mathbb{R}^N)^{\otimes 3}$$

Multi-Species Spin Glasses

- Formally, each coordinate part of a **species** $s \in \mathcal{S} = \{1, \dots, r\}$

$$[N] = \mathcal{I}_1 \cup \dots \cup \mathcal{I}_r, \quad |\mathcal{I}_s| = \lambda_s N$$

Multi-Species Spin Glasses

- Formally, each coordinate part of a **species** $s \in \mathcal{S} = \{1, \dots, r\}$

$$[N] = \mathcal{I}_1 \cup \dots \cup \mathcal{I}_r, \quad |\mathcal{I}_s| = \lambda_s N$$

- Interaction weights $\gamma_2, \gamma_3, \dots$ now $(\gamma_{s_1, s_2})_{s_1, s_2 \in \mathcal{S}}, (\gamma_{s_1, s_2, s_3})_{s_1, s_2, s_3 \in \mathcal{S}}, \dots$

Multi-Species Spin Glasses

- Formally, each coordinate part of a **species** $s \in \mathcal{S} = \{1, \dots, r\}$

$$[N] = \mathcal{I}_1 \cup \dots \cup \mathcal{I}_r, \quad |\mathcal{I}_s| = \lambda_s N$$

- Interaction weights $\gamma_2, \gamma_3, \dots$ now $(\gamma_{s_1, s_2})_{s_1, s_2 \in \mathcal{S}}, (\gamma_{s_1, s_2, s_3})_{s_1, s_2, s_3 \in \mathcal{S}}, \dots$
- ξ now **multivariate** polynomial in (q_1, \dots, q_r)

Multi-Species Spin Glasses

- Formally, each coordinate part of a **species** $s \in \mathcal{S} = \{1, \dots, r\}$

$$[N] = \mathcal{I}_1 \cup \dots \cup \mathcal{I}_r, \quad |\mathcal{I}_s| = \lambda_s N$$

- Interaction weights $\gamma_2, \gamma_3, \dots$ now $(\gamma_{s_1, s_2})_{s_1, s_2 \in \mathcal{S}}, (\gamma_{s_1, s_2, s_3})_{s_1, s_2, s_3 \in \mathcal{S}}, \dots$
- ξ now **multivariate** polynomial in (q_1, \dots, q_r)
- Goal: optimize H_N over **product of spheres**

$$\mathbb{T}_N = \left\{ \sigma \in \mathbb{R}^N : \|\sigma|_{\mathcal{I}_s}\|_2^2 = \lambda_s N \quad \forall s \in \mathcal{S} \right\}$$

Multi-Species Spin Glasses

- Formally, each coordinate part of a **species** $s \in \mathcal{S} = \{1, \dots, r\}$

$$[N] = \mathcal{I}_1 \cup \dots \cup \mathcal{I}_r, \quad |\mathcal{I}_s| = \lambda_s N$$

- Interaction weights $\gamma_2, \gamma_3, \dots$ now $(\gamma_{s_1, s_2})_{s_1, s_2 \in \mathcal{S}}, (\gamma_{s_1, s_2, s_3})_{s_1, s_2, s_3 \in \mathcal{S}}, \dots$
- ξ now **multivariate** polynomial in (q_1, \dots, q_r)
- Goal: optimize H_N over **product of spheres**

$$\mathbb{T}_N = \left\{ \sigma \in \mathbb{R}^N : \|\sigma|_{\mathcal{I}_s}\|_2^2 = \lambda_s N \quad \forall s \in \mathcal{S} \right\}$$

- OPT known for **convex** or **pure** ξ (Panchenko 15, Subag 21, Bates-Sohn 22)

Multi-Species Spin Glasses

- Formally, each coordinate part of a **species** $s \in \mathcal{S} = \{1, \dots, r\}$

$$[N] = \mathcal{I}_1 \cup \dots \cup \mathcal{I}_r, \quad |\mathcal{I}_s| = \lambda_s N$$

- Interaction weights $\gamma_2, \gamma_3, \dots$ now $(\gamma_{s_1, s_2})_{s_1, s_2 \in \mathcal{S}}, (\gamma_{s_1, s_2, s_3})_{s_1, s_2, s_3 \in \mathcal{S}}, \dots$
- ξ now **multivariate** polynomial in (q_1, \dots, q_r)
- Goal: optimize H_N over **product of spheres**

$$\mathbb{T}_N = \left\{ \sigma \in \mathbb{R}^N : \|\sigma|_{\mathcal{I}_s}\|_2^2 = \lambda_s N \quad \forall s \in \mathcal{S} \right\}$$

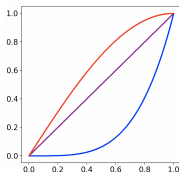
- OPT known for **convex** or **pure** ξ (Panchenko 15, Subag 21, Bates-Sohn 22)
- ALG has richer behavior than in one species

Multi-Species Algorithms

- Optimizing on product of spheres \Rightarrow track radius for each species

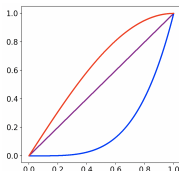
Multi-Species Algorithms

- Optimizing on product of spheres \Rightarrow track radius for each species
 - 2 species: **radius schedule** is up-right path from $(0,0)$ to $(1,1)$



Multi-Species Algorithms

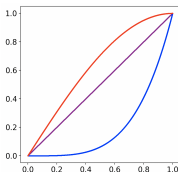
- Optimizing on product of spheres \Rightarrow track radius for each species
 - 2 species: **radius schedule** is up-right path from $(0, 0)$ to $(1, 1)$



- In general, radius schedule is coordinate-increasing $\Phi : [0, 1] \rightarrow [0, 1]^{\mathcal{S}}$

Multi-Species Algorithms

- Optimizing on product of spheres \Rightarrow track radius for each species
 - 2 species: **radius schedule** is up-right path from $(0,0)$ to $(1,1)$



- In general, radius schedule is coordinate-increasing $\Phi : [0, 1] \rightarrow [0, 1]^{\mathcal{S}}$
- Each Φ gives algorithm taking small orthogonal steps **in each species**
- Algorithm value

$$\mathbb{A}(\Phi) \equiv \sum_{s \in \mathcal{S}} \lambda_s \int_0^1 \sqrt{(\partial_{q_s} \xi \circ \Phi)'(q) \Phi'_s(q)} dq$$

Multi-Species Algorithmic Threshold

Theorem (Huang-S 23+)

Define

$$\text{ALG} = \sup_{\substack{\phi: [0,1] \rightarrow [0,1]^{\mathcal{S}} \\ \text{increasing, differentiable}}} \sum_{s \in \mathcal{S}} \lambda_s \int_0^1 \sqrt{(\partial_{q_s} \xi \circ \phi)'(q) \phi'_s(q)} \, dq$$

Multi-Species Algorithmic Threshold

Theorem (Huang-S 23+)

Define

$$\text{ALG} = \sup_{\substack{\Phi: [0,1] \rightarrow [0,1]^{\mathcal{S}} \\ \text{increasing, differentiable}}} \sum_{s \in \mathcal{S}} \lambda_s \int_0^1 \sqrt{(\partial_{q_s} \xi \circ \Phi)'(q) \Phi'_s(q)} \, dq$$

- An explicit $O(1)$ -Lipschitz algorithm achieves ALG w.h.p.
- No $O(1)$ -Lipschitz algorithm beats ALG with probability e^{-cN} .

Multi-Species Algorithmic Threshold

Theorem (Huang-S 23+)

Define

$$\text{ALG} = \sup_{\substack{\phi: [0,1] \rightarrow [0,1]^{\mathcal{S}} \\ \text{increasing, differentiable}}} \sum_{s \in \mathcal{S}} \lambda_s \int_0^1 \sqrt{(\partial_{q_s} \xi \circ \phi)'(q) \phi'_s(q)} \, dq$$

- An explicit $O(1)$ -Lipschitz algorithm achieves ALG w.h.p.
- No $O(1)$ -Lipschitz algorithm beats ALG with probability e^{-cN} .

(More general threshold with external fields too)

Multi-Species Algorithmic Threshold

Theorem (Huang-S 23+)

Define

$$\text{ALG} = \sup_{\substack{\Phi: [0,1] \rightarrow [0,1]^{\mathcal{S}} \\ \text{increasing, differentiable}}} \sum_{s \in \mathcal{S}} \lambda_s \int_0^1 \sqrt{(\partial_{q_s} \xi \circ \Phi)'(q) \Phi'_s(q)} \, dq$$

- An explicit $O(1)$ -Lipschitz algorithm achieves ALG w.h.p.
- No $O(1)$ -Lipschitz algorithm beats ALG with probability e^{-cN} .

(More general threshold with external fields too)

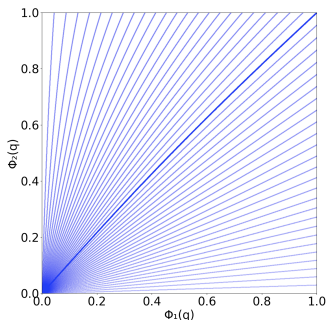
Theorem (Huang-S 23+)

The variational formula has a maximizer Φ , which solves an explicit ODE.

Variational Problem Example

Consider $(\lambda_1, \lambda_2) = (1/3, 2/3)$ and

$$\xi(q_1, q_2) = (\lambda_1 q_1)^2 + (\lambda_1 q_1)(\lambda_2 q_1) + (\lambda_2 q_1)^2 + (\lambda_1 q_1)^4 + (\lambda_1 q_1)(\lambda_2 q_2)^3$$

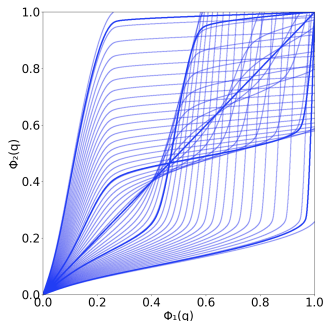


Some ODE solutions. Optimal $\Phi : [0, 1] \rightarrow [0, 1]^2$ in bold

Algorithmic Symmetry Breaking

Optimal Φ may be asymmetric, even when model is symmetric!

$$\lambda_1 = \lambda_2 = \frac{1}{2}, \quad \xi(q_1, q_2) = (3q_1)^2 + (3q_1)(3q_2) + (3q_2)^2 + (3q_1)^4 + (3q_2)^4$$



The plot thickens...

Pure Multi-Species Models

- Models where

$$\xi(q_1, \dots, q_r) = q_1^{a_1} q_2^{a_2} \cdots q_r^{a_r}$$

- Example: bipartite SK $\xi(q_1, q_2) = q_1 q_2$

Pure Multi-Species Models

- Models where

$$\xi(q_1, \dots, q_r) = q_1^{a_1} q_2^{a_2} \cdots q_r^{a_r}$$

- Example: bipartite SK $\xi(q_1, q_2) = q_1 q_2$

- Optimal Φ is **polynomial**

$$\Phi(q) = (q^{b_1}, \dots, q^{b_r})$$

- In this case, $\text{ALG} = E_\infty$ has explicit non-variational formula.
- Langevin dynamics is believed to reach the same threshold!

Summary

- We determine algorithmic threshold of $O(1)$ -Lipschitz algorithms for optimizing multi-species spherical spin glasses

Summary

- We determine algorithmic threshold of $O(1)$ -Lipschitz algorithms for optimizing multi-species spherical spin glasses
- Branching OGP matches Subag algorithm for generic reason

Summary

- We determine algorithmic threshold of $O(1)$ -Lipschitz algorithms for optimizing multi-species spherical spin glasses
- Branching OGP matches Subag algorithm for generic reason
- Geometric description of ALG: largest value whose super-level set contains densely-branching ultrametric tree
 - Optimal algorithms climb this tree
 - Absence of this tree implies hardness by BOGP

Summary

- We determine algorithmic threshold of $O(1)$ -Lipschitz algorithms for optimizing multi-species spherical spin glasses
- Branching OGP matches Subag algorithm for generic reason
- Geometric description of ALG: largest value whose super-level set contains densely-branching ultrametric tree
 - Optimal algorithms climb this tree
 - Absence of this tree implies hardness by BOGP
 - Comparison with OPT ultrametricity: ALG trees must branch continuously, OPT trees may not

Summary

- We determine algorithmic threshold of $O(1)$ -Lipschitz algorithms for optimizing multi-species spherical spin glasses
- Branching OGP matches Subag algorithm for generic reason
- Geometric description of ALG: largest value whose super-level set contains densely-branching ultrametric tree
 - Optimal algorithms climb this tree
 - Absence of this tree implies hardness by BOGP
 - Comparison with OPT ultrametricity: ALG trees must branch continuously, OPT trees may not

Thank you!

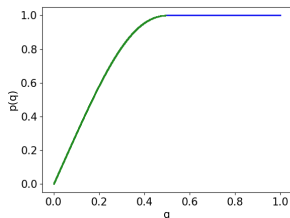
Models with Linear Terms

Suppose model has 1-spin interaction (external field)

$$H_N(\sigma) = \sum_{p=1}^P \frac{\gamma_p}{N^{(p-1)/2}} \langle \mathbf{G}^{(p)}, \sigma^{\otimes p} \rangle \quad \xi(q) = \sum_{p=1}^P \gamma_p^2 q^p$$

Then

$$\text{ALG} = \text{BOGP} = \sup_{\substack{p: [0,1] \rightarrow [0,1] \\ \text{increasing, differentiable}}} \int_0^1 \sqrt{(p\xi')'(q)} \, dq$$



Optimal p for $\xi(q) = q^4 + q$

Multi-Species Algorithmic Threshold with Linear Terms

Theorem (Huang-S 23+)

Define

$$\text{ALG} = \sup_{\substack{p:[0,1] \rightarrow [0,1] \\ \Phi:[0,1] \rightarrow [0,1]^{\mathcal{S}} \\ \text{increasing, differentiable}}} \sum_{s \in \mathcal{S}} \lambda_s \int_0^1 \sqrt{(p \times \partial_{q_s} \xi \circ \Phi)'(q) \Phi'_s(q)} dq$$

- An explicit $O(1)$ -Lipschitz algorithm achieves ALG w.h.p.
- No $O(1)$ -Lipschitz algorithm beats ALG with probability e^{-cN}

Theorem (Huang-S 23+)

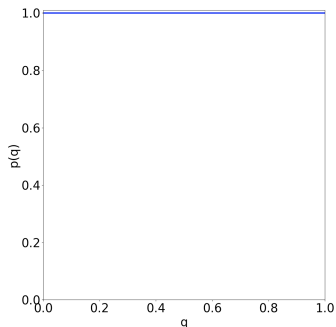
This variational problem has a maximizer (p, Φ) .

- The maximizer solves an explicit ODE.
- If ξ has no 1-spin interactions, then $p \equiv 1$.

Variational Problem Example: No Linear Term

Consider $(\lambda_1, \lambda_2) = (1/3, 2/3)$

$$\xi(q_1, q_2) = (\lambda_1 q_1)^2 + (\lambda_1 q_1)(\lambda_2 q_1) + (\lambda_2 q_1)^2 + (\lambda_1 q_1)^4 + (\lambda_1 q_1)(\lambda_2 q_2)^3$$



Optimal $p : [0, 1] \rightarrow [0, 1]$

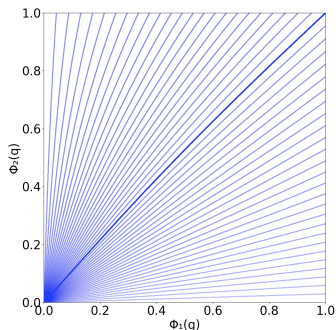
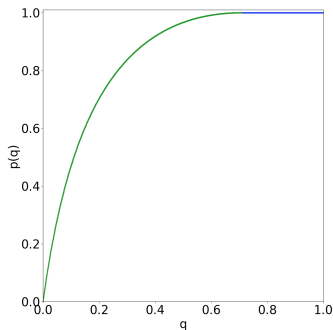


Image of optimal $\Phi : [0, 1] \rightarrow [0, 1]^2$ in bold

Variational Problem Example: Small Linear Term

Consider $(\lambda_1, \lambda_2) = (1/3, 2/3)$

$$\xi(q_1, q_2) = (\lambda_1 q_1)^2 + (\lambda_1 q_1)(\lambda_2 q_1) + (\lambda_2 q_1)^2 + (\lambda_1 q_1)^4 + (\lambda_1 q_1)(\lambda_2 q_2)^3 \\ + 0.05(\lambda_1 q_1) + 0.5(\lambda_2 q_2)$$



Optimal $p : [0, 1] \rightarrow [0, 1]$

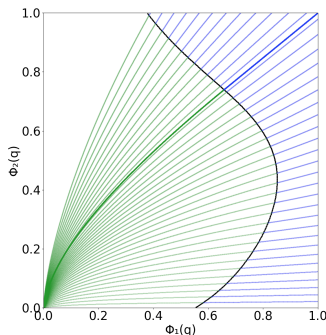
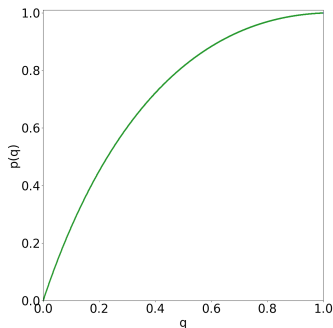


Image of optimal $\Phi : [0, 1] \rightarrow [0, 1]^2$ in bold

Variational Problem Example: Large Linear Term

Consider $(\lambda_1, \lambda_2) = (1/3, 2/3)$

$$\xi(q_1, q_2) = (\lambda_1 q_1)^2 + (\lambda_1 q_1)(\lambda_2 q_1) + (\lambda_2 q_1)^2 + (\lambda_1 q_1)^4 + (\lambda_1 q_1)(\lambda_2 q_2)^3 \\ + 0.2(\lambda_1 q_1) + 1.8(\lambda_2 q_2)$$



Optimal $p : [0, 1] \rightarrow [0, 1]$

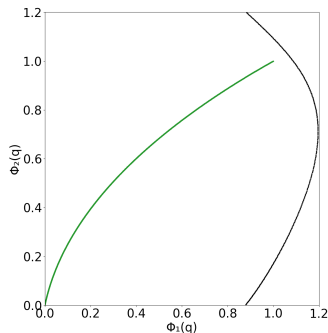


Image of optimal $\Phi : [0, 1] \rightarrow [0, 1]^2$